

CJ Series EtherNet/IP™ Connection Guide

OMRON Corporation ZW-series Displacement Sensor

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1. Related Manuals

The table below lists the manuals related to this document.

To ensure system safety, make sure to always read and heed the information provided in all Safety Precautions, Precautions for Safe Use, and Precaution for Correct Use of manuals for each device which is used in the system.

Cat. No.	Model	Manual name
W472	CJ2H-CPU6[]-EIP	CJ-series CJ2 CPU Unit Hardware User's Manual
	CJ2H-CPU6[]	
	CJ2M-CPU[][]	
W473	CJ2H-CPU6[]-EIP	CJ-series CJ2 CPU Unit Software User's Manual
	CJ2H-CPU6[]	
	CJ2M-CPU[][]	
W465	CJ1W-EIP21	EtherNet/IP™ Unit Operation Manual
	CJ2H-CPU6[]-EIP	
	CJ2M-CPU3[]	
W446	-	CX-Programmer Operation Manual
Z332	ZW-CE1[]	ZW Series Displacement Sensor (Confocal Fiber Type)
		User's Manual

2. Terms and Definitions

Term	Explanation and Definition
Tag data link	A function that enables cyclic tag data exchanges on an EtherNet/IP network between PLCs or between PLCs and with other devices without using a user program in the PLCs.
Tag	A tag is a unit that is used to exchange data with tag data links. Data is exchanged between the local network variables and remote network variables specified in the tags or between specified I/O memory areas.
Tag set	When a connection is established, from 1 to 8 tags (including Controller status) is configured as a tag set. Each tag set represents the data that is linked for a tag data link connection.
Connection	A connection is used to exchange data as a unit within which data synchronicity is maintained. Thus, data synchronicity is maintained for all the data exchanged for the tags in one data set.
Originator and Target	To perform tag data links, one node requests the opening of a communications line called "connection" to perform tag data links. The node that requests opening the connection is called "originator", and the node that receives the request is called "target".
Node	With EtherNet/IP network, 1 node is 1 EtherNet/IP port.
Tag data link	The tag data link parameter is the setting data to perform the tag data
_parameter	link. It includes the data to set tags, tag sets, and connections.
EDS file	A file that contains the I/O points of EtherNet/IP devices and the parameters that can be set via EtherNet/IP.

3. Remarks

- (1) Understand the specifications of devices which are used in the system. Allow some margin for ratings and performance. Provide safety measures, such as installing safety circuit in order to ensure safety and minimize risks of abnormal occurrence.
- (2) To ensure system safety, always read and heed the information provided in all Safety Precautions, Precautions for Safe Use, and Precaution for Correct Use of manuals for each device used in the system.
- (3) The users are encouraged to confirm the standards and regulations that the system must conform to.
- (4) It is prohibited to copy, to reproduce, and to distribute a part of or whole part of this document without the permission of OMRON Corporation.
- (5) This document provides the latest information as of April 2013. The information on this manual is subject to change without notice for improvement.

The following notation is used in this document.



WARNING

Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury. Additionally, there may be severe property damage.



Caution

Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury, or property damage.



Precautions for Safe Use

Precautions on what to do and what not to do to ensure safe usage of the product.



Precautions for Correct Use

Precautions on what to do and what not to do to ensure proper operation and performance.



Additional Information

Additional information to read as required.

This information is provided to increase understanding or make operation easier.

Symbols



The triangle symbol indicates precautions (including warnings). The specific operation is shown in the triangle and explained in text. This example indicates a general precaution.

4. Overview

This document describes the procedure to connect the Displacement Sensor (ZW series) of OMRON Corporation (hereinafter referred to as OMRON) with CJ-series Programmable Controller + Ethernet/IP Unit (hereinafter referred to as the PLC), and the procedure to check their connection.

Refer to Section 6. Connection Procedure to understand the setting method and key points to connect the devices via EtherNet I/P.

In this document, CJ-series EtherNet/IP Unit and the built-in EtherNet/IP port of CJ-series CJ2 CPU Unit are collectively called as the "EtherNet/IP Unit".

5. Applicable Devices and Support Software

5.1. Applicable Devices

The applicable devices are as follows:

Manufacturer	Name	Model
OMRON	CJ2 CPU Unit	CJ2[]-CPU[][]
OMRON	EtherNet/IP Unit	CJ1W-EIP21
		CJ2H-CPU6[]-EIP
		CJ2M-CPU3[]
OMRON	Confocal Fiber Type	ZW-CE1[]
	Displacement Sensor Controller	ZW-CE1[]T
OMRON	Sensor Head	ZW-S[][]



Additional Information

As applicable devices above, the devices with the models and versions listed in Section 5.2. are actually used in this document to describe the procedure for connecting devices and checking the connection.

You cannot use devices with versions lower than the versions listed in Section 5.2.

To use the above devices with versions not listed in Section 5.2 or versions higher than those listed in Section 5.2, check the differences in the specifications by referring to the manuals before operating the devices.

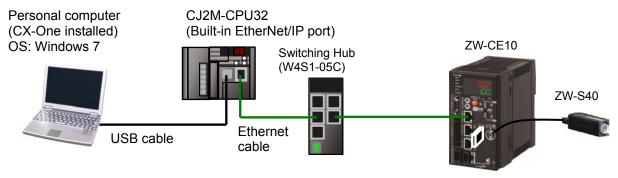


Additional Information

This document describes the procedure to establish the network connection. Except for the connection procedure, it does not provide information on operation, installation or wiring method. It also does not describe the functionality or operation of the devices. Refer to the manuals or contact your OMRON representative.

5.2. Device Configuration

The hardware components to reproduce the connection procedure of this document are as follows:



Calibration ROM

Manufacturer	Name	Model	Version
OMRON	CPU Unit	CJ2M-CPU32	Ver.2.0
	(Built-in EtherNet/IP port)	(with built-in CJ2M-EIP21)	(Ver.2.1)
OMRON	Power Supply Unit	CJ1W-PA202	
OMRON	Switching Hub	W4S1-05C	Ver.1.0
OMRON	CX-One	CXONE-AL[][]C-V4	Ver.4.[][]
		/AL[][]D-V4	
OMRON	CX-Programmer	(Included in CX-One.)	Ver.9.41
OMRON	Network Configurator	(Included in CX-One.)	Ver.3.55
-	Personal computer (OS: Windows 7)	-	
	USB cable	 -	
OMRON	Ethernet cable (with industrial Ethernet connector)	XS5W-T421-[]M[]-K	
OMRON	Displacement Sensor Controller	ZW-CE10	Ver.1.110
OMRON	Displacement Sensor Sensor Head	ZW-S40	
OMRON	Calibration ROM	(Included with Sensor Head.)	
OMRON	Recommended power supply: 24VDC 2.5A 60W	S8VS-06024	



Precautions for Correct Use

Update the CX-Programmer and Network Configurator to the versions specified in this section or higher versions using the auto update function.

If a version not specified in this section is used, the procedures described in Section 6 and subsequent sections may not be applicable. In that case, use the equivalent procedures described in the CX-Programmer Operation Manual (Cat. No. W446) and Network Configurator Online Help.



Additional Information

The system configuration in this document uses USB for the connection between the personal computer and PLC. When installing the USB driver, please refer to *A-5 Installing the USB Driver* in the CJ-series *CJ2 CPU Unit Hardware User's Manual* (Cat. No. W472).

This section explains the procedure for connecting the Displacement Sensor to the PLC via EtherNet/IP.

6.1. EtherNet/IP Communications Settings

The settings shown in the table below are used to explain the procedure for connecting the PLC.

This document explains the procedure for setting up the PLC and Displacement Sensor from the factory default setting. For the initialization, refer to Section 7 Initialization Method.

6.1.1. Settings

The settings of the PLC (EtherNet/IP Unit) and the Displacement Sensor are as follows:

	PLC (EtherNet/IP Unit)	Displacement Sensor
	(node 1)	(node 2)
Unit number	0	-
Node address	1	2
IP address	192.168.250.1	192.168.250.2
Subnet mask	255.255.255.0	255.255.255.0 (default)
MEMLNK	-	EIP (EtherNet/IP)
(Memory link function)		

6.1.2. Tag Data Link Allocation

The tag data link allocation of the Displacement Sensor is as follows:

	Output area		Input area
D10000	$(PLC \to Displacement$	D10100	(Displacement Sensor →
	Sensor)		PLC)
D10011	24 bytes	D10127	56 bytes

•Output area (PLC → Displacement Sensor)

											Bit						
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Description
D10000															SYNC	EXE	Control
D10001																	input ^{*1} (2 words)
D10002														LIGHT OFF	RESET1		Control input *2
D10003									ZERO CLR_T4	ZERO CLR_T3	ZERO CLR_T2	_	ZERO1 _T4	ZERO1 _T3	ZERO1 _T2		(2 words)
D10004																	Control
D10005																	input ^{*3} (2 words)
D10006 D10007		Command code (2 words)												-			
D10008									Cor	nmand	param	eter 1					Command
D10009									Cor	nmand	param	eter 2					parameters
D10010 D10011									Cor	mmand	param	eter 3					(Up to 4 words)

^{*1:} Sensor head common control signal

^{*2:} Sensor head 1 control signal

^{*3:} Sensor head 2 control signal (Reserved)

Input area (Displacement Sensor → PLC)

	Bit																
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Description
D10100	BANK 1_E	BANK 1_D	BANK 1_C	BANK 1_B	BANK 1_A							RUN		READY	SYNC FLG	FLG	Control output *1
D10101																ERR	(2 words)
D10102										OR1		ENABLE1	STABLIT Y1	LIGHT1	RESETS TAT1	HOLDST AT1	Control
D10103	LOW1 _T4	PASS 1 _T4	HIGH 1_T4	LOW1 _T3	PASS 1 _T3	HIGH 1_T3		PASS 1 _T2	HIGH 1_T2		PASS 1 T1	HIGH1_T 1	ZEROST AT_T4	ZEROST AT_T3	ZEROST AT_T2	ZEROST AT_T1	output *2 (2 words)
D10104																	Control
D10105																	output *3 (2 words)
D10106 D10107	Command code (2 Words)												-				
D10108							Re	spor	ise c	ode	(2 w	ords)					-
D10109 D10110											•						
D10110							Re	espor	nse d	ata	(2 w	ords)					_
D10112									utpu	t da	ta 0						
D10113									ratpa	t dd							
D10114 D10115								C	utpu	t da	ta 1						
D10115																	
D10117								C	utpu	t da	ta 2						
D10118									utpu	t da	ta 3						
D10119									ratpa	t dd							Output data (16 words)
D10120								C	utpu	t da	ta 4						
D10121 D10122											. –						
D10123								С	utpu	t da	ta 5						
D10124								Γ	utpu	t da	ta 6						
D10125	_								агри	· uu	0						.
D10126 D10127								C	utpu	t da	ta 7						
DIVIZI																	

- *1: Sensor head common status signal
- *2: Sensor head 1 status signal
- *3: Sensor head 2 status signal (Reserved)

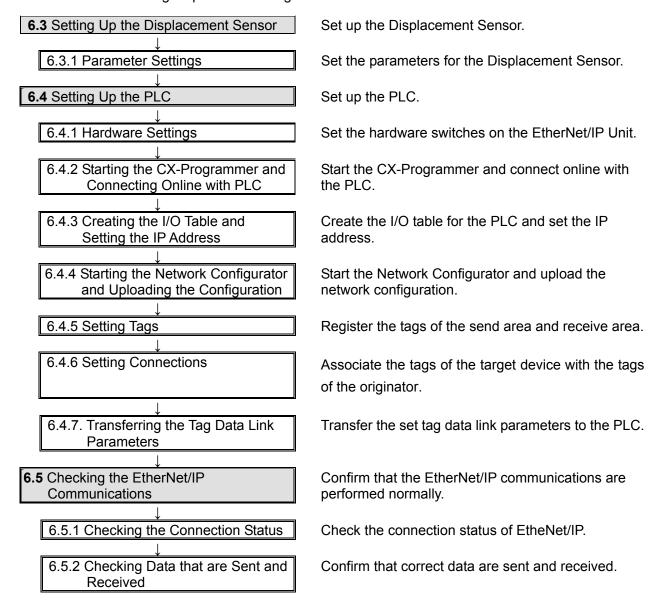


Additional Information

For details on the command codes and response codes, refer to 6-3 Ethernet/IP Connection under Chapter 6 Communications with External Devices in the ZW Series Displacement Sensor (Confocal Fiber Type) User's Manual (Cat. No. Z332).

6.2. Work Flow

Take the following steps to set the tag data link for EtherNet/IP.



6.3. Setting Up the Displacement Sensor

Set up the Displacement Sensor.

6.3.1. Parameter Settings

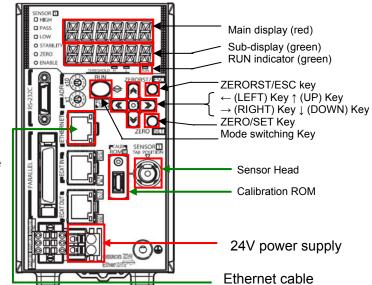
Set the parameters for the Displacement Sensor.

1 Check the keys and display used to set parameters for the Displacement Sensor.

Connect the Controller to the Sensor Head and connect the Calibration ROM.

Connect the Ethernet cable.

Turn ON the power supply to the Displacement Sensor.



After the startup screen is displayed, the RUN mode screen is displayed.
The RUN indicator is lit as shown on the right.
Hold down the **Mode switching** Key for two seconds.



Key for two seconds.

A confirmation screen for mode switching is displayed. Press the **ZERO/SET** Key.



1000 1110 11110/0111 110/ 011001

The RUN mode screen is displayed.

The RUN indicator is not lit as shown on the right.

Press → (RIGHT) Key or ← (LEFT) Key to change the main display content from SENS to SYSTEM.

Press the **ZERO/SET** Key.



Press the \rightarrow (RIGHT) Key or \leftarrow (LEFT) Key.



Press the **ZERO/SET** Key once.

5 SAVE is displayed on the main display.

Press → (RIGHT) Key or ← (LEFT) Key and change the main display content from SAVE to COM.



Press the \rightarrow (RIGHT) Key or \leftarrow (LEFT) Key.



Press the **ZERO/SET** Key.



9 IP2 is displayed on the main display.

Press the **ZERO/SET** Key.

Confirm that 168 is displayed on the sub-display.

- *If the setting value is different, change the value by referring to step 11 and step 12.
- *In this step, you set 168 that is the second octet of IP address 192.168.250.2.

Press the **ZERORST/ESC** Key once. The first screen in this step is displayed again.
Press the → (RIGHT) Key once.



Press the **ZERO/SET** Key once.



Press the **ZERORST/ESC** Key once.

IP2 is displayed.

Press the \rightarrow (RIGHT) Key once.

10 IP3 is displayed on the main display.

Press the **ZERO/SET** Key.

Confirm that 250 is displayed on the sub-display.

- *If the setting value is different, change the value by referring to step 11 and step 12.
- *In this step, you set 250 that is the third octet of IP address 192.168.250.2.

Press the **ZERORST/ESC** Key once. The first screen in this step is displayed again. Press the \rightarrow (RIGHT) Key once.



Press the **ZERO/SET** Key once.



Press the **ZERORST/ESC** Key once.

IP3 is displayed.

Press the \rightarrow (RIGHT) key once.

11 IP4 is displayed on the main display.

Press the **ZERO/SET** Key.

The default value is displayed on the sub-display.

Press the **ZERO/SET** Key.

The sub-display content changes and you can change the values.

Select a digit whose value you want to change by pressing the \rightarrow (RIGHT) or \leftarrow (LEFT) Key. You can change the value of a blinking digit.

Change the value by pressing the \uparrow (UP) or \downarrow (DOWN) Key. Change to 000002.



Press the **ZERO/SET** Key once.



Press the **ZERO/SET** Key once.



Press the \rightarrow (RIGHT) or \leftarrow (LEFT) Key. Press the \uparrow (UP) or \downarrow (DOWN) Key.

12 000002 is displayed on the sub-display.

Press the **ZERO/SET** Key.

2 is displayed on the sub-display.

*In this step, you set 2 that is the fourth octet of IP address 192.168.250.2.

Press **ZERORST/ESC** Key once. The first screen in step 11 is displayed again.

Press the **ZERORST/ESC** Key once.



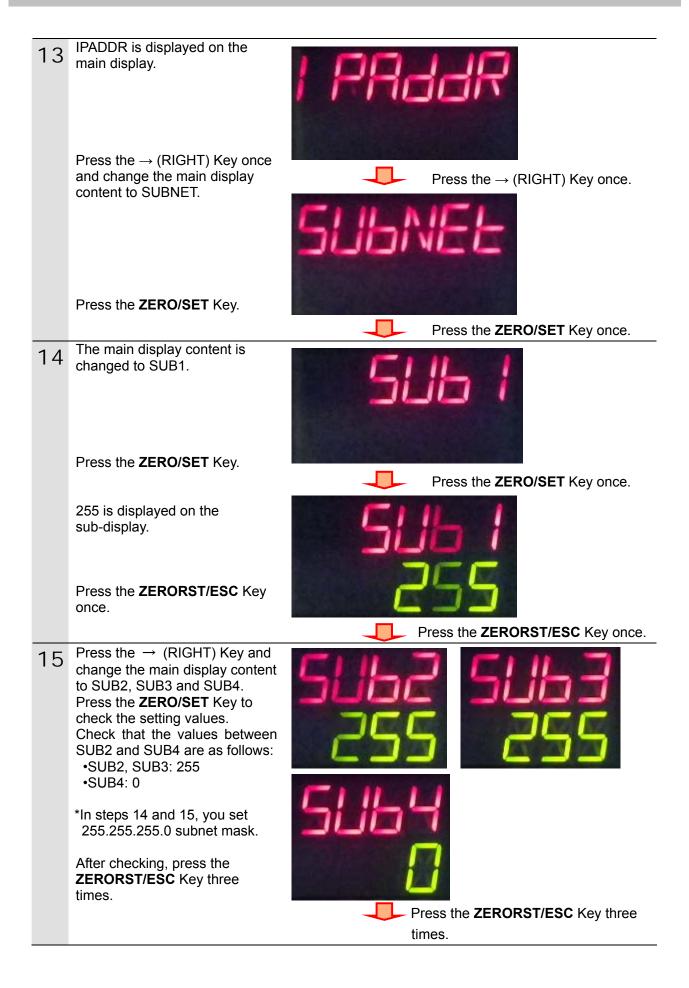
Press the **ZERO/SET** Key once.

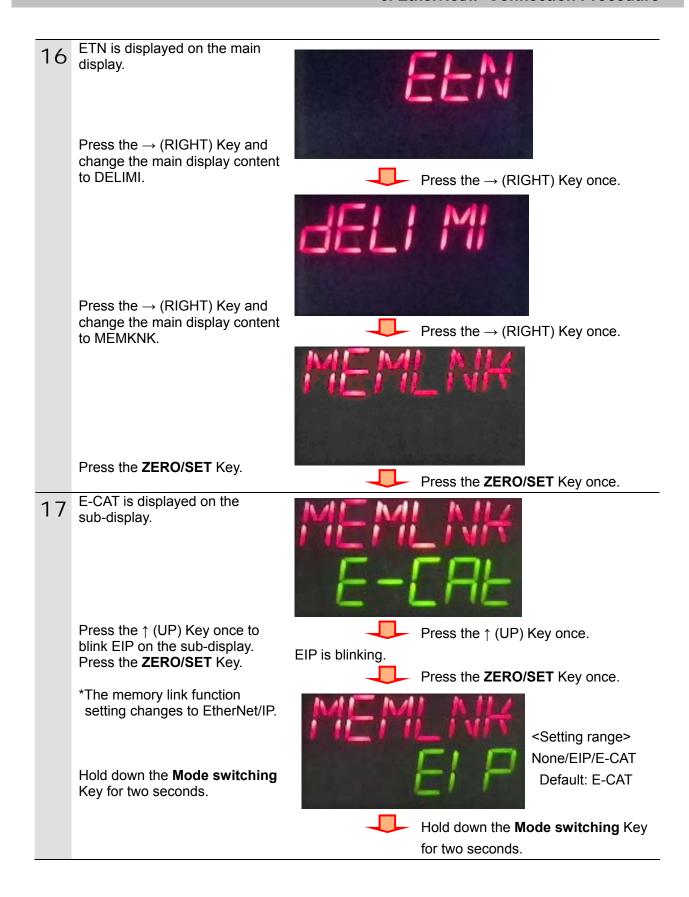


Press the **ZERORST/ESC** Key once.

IP4 is displayed.

Press the **ZERORST/ESC** Key once.





A confirmation screen for mode switching is displayed.

Press the **ZERO/SET** Key.

The save confirmation screen is displayed.

Press the **ZERO/SET** Key.

The RUN mode screen is displayed.



Pro

Press the **ZERO/SET** Key once.





Press the **ZERO/SET** Key once.



19 Cycle the power supply to the Displacement Sensor.

*The new settings will take effect after restarting.

6.4. Setting Up the PLC

Set up the PLC.

6.4.1. Hardware Settings

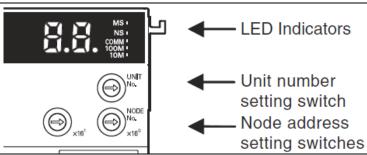
Set the hardware switches on the EtherNet/IP Unit.



Precautions for Correct Use

Make sure that the power supply is OFF when you perform the setting up.

- 1 Make sure that the PLC power is OFF.
 - *If the power supply is turned ON, the following procedure may not be applicable.
- Refer to the right figure and check the hardware switches located on the front panel of the EtherNet/IP Unit.



3 Set the Unit number setting switch to 0.

The unit number is used to identify individual CPU Bus Units when more than one CPU Bus Unit is mounted to the same PLC. Use a small screwdriver to make the setting, taking care not to damage the rotary switch. The unit number is factory-set to 0.



4 Set the node address setting switches to the following default values.

[NODE No.x16¹]: 0 [NODE No.x16⁰]: 1

*Set the IP address to 192.168.250.1.

*By default, the upper three octets are fixed to 192.168.250, and the values set with the node address setting switches are the fourth octet of the local IP address.

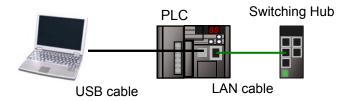
With the FINS communications service, when there are multiple EtherNet/IP Units connected to the Ethernet network, the EtherNet/IP Units are identified by node addresses. Use the node address switches to set the node address between 01 and FE hexadecimal (1 to 254 decimal).Do not set a number that has already been set for another node on the same network.



The left switch sets the sixteens digit (most significant digit) and the right switch sets the ones digit (least significant digit). The node address is factory-set to 01.

Default IP address = 192.168.250.node address With the factory-default node address setting of 01, the default IP address is 192.168.250.1.

Connect the LAN cable to the EtherNet/IP port of the PLC, and connect the USB cable to the USB port. As shown in 5.2.
Device Configuration, connect the personal computer,
Switching Hub and PLC.



Turn ON the power supply to the PLC.

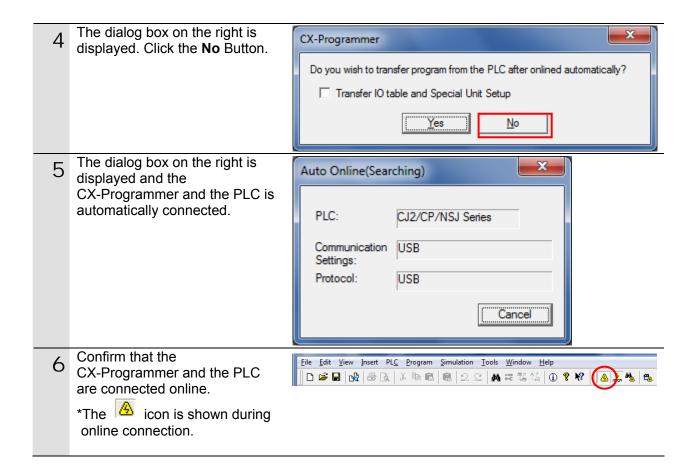
The set IP address is displayed on the seven-segment LED indicators from right to left. Afterwards, the rightmost 8 bits of the IP address are displayed in hexadecimal during normal operation.

6.4.2. Starting the CX-Programmer and Connecting Online with PLC

Start the CX-Programmer and connect online with the PLC.

Install the CX-One and USB driver in the personal computer beforehand.

Start the CX-Programmer. Select Auto Online - Direct PLC Tools Help Online from the PLC Menu. <u>Direct</u> Online Auto Online P1L-Ethernet Online EtherNet/IP Node Online The Direct Online Dialog Box is Direct Online displayed. Select the USB Connection Option for the Connection Type and click the Goes online automatically. Select connection type and press [Connect] button. Connect Button. Connection Type C Serial connection (also when using USB-Serial conversion cable) Serial port of PC COM1 Connects at baud rate 115,200 bps USB connection Connection will automatically be made to the PLC connected directly to the PC via USB cable. Please select ""Serial connection"" when using USB-Serial conversion cable. Connect Cancel





Additional Information

If the CX-Programmer and PLC are not connected online, please check the connection of the cable. Or, return to step 2, check the settings and perform each step again.

Refer to Connecting Directly to a CJ2 CPU Unit Using a USB Cable in Chapter 3
Communications in PART 3: CX-Server Runtime of the CX-Programmer Operation Manual
(Cat. No. W466) for details.



Additional Information

The dialogs explained in the following procedures may not be displayed depending on the environmental setting of CX-Programmer.

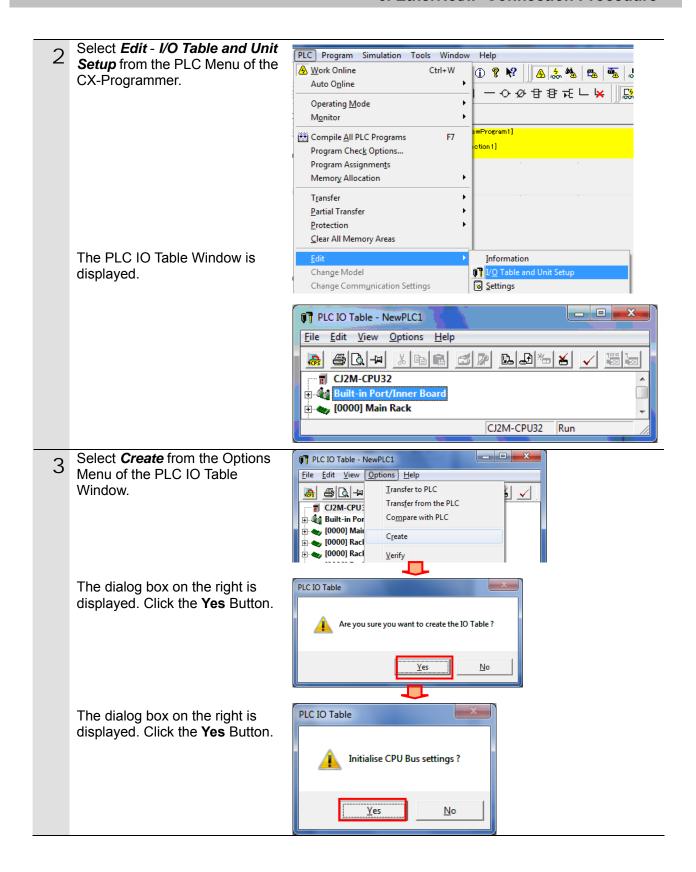
For details on the environmental setting, refer to *Options and Preferences* in *Chapter 3 Project Reference* in *PART 1: CX-Programmer* of the *CX-Programmer Operation Manual* (Cat. No. W466).

This document explains the setting procedure when the setting item "Confirm all operations affecting the PLC" is selected.

6.4.3. Creating the I/O Table and Setting the IP Address

Create the I/O table for the PLC and set the IP address.

If the operating mode of the PLC **⊤** x is RUN Mode or Monitor Mode, change it to Program Mode by - Run Mode following steps (1) to (3). <u>File Edit View Insert PLC Program Simulation Tools Window</u> 🗅 😅 🔲 🕍 🚳 🖟 Work Online Ctrl+W [B (1) ? N? A 🕹 Auto Online a 🛠 Q Q | 🏢 📴 🚃 <u>D</u>ebug Monitor Monitor Ctrl+3 Compile All PLC Programs ⊟ 🍓 NewProject Run Run Ctrl+4 (1)Select Operating Mode -Program Check Options... Program from the PLC Menu 🛂 Data Types Program Assignmen<u>t</u>s Memory Allocation 🤧 Symbols of CX-Programmer. (2)The dialog box on the right is displayed. Click the Yes Button. Make sure that there aren't any problems if the PLC is stopped. Do you wish to switch the PLC into program mode? *Refer to Additional Information on the previous page for the settings concerning the dialog <u>Y</u>es <u>N</u>o display. (3)Confirm that Stop/Program ▼ X Mode is shown on the right ⊢...ॡ NewProject side of the PLC model in the □ I NewPLC1[CJ2M] Sop/Program Mode Project Workspace of Data Types CX-Programmer. Symbols



The Transfer from PLC Dialog Box is displayed. Select the I/O Table Check Box and the SIO Unit Parameters Check Box, and click the **Transfer** Button. Transfer from PLC

Select the transfer target data and press the [Transfer] button.
Comment information is deleted if IO Table is transferred.

✓ IO Table

✓ SIO Unit Parameters

Transfer

Cancel

Transfer from PLC

Transferring.

Cancel

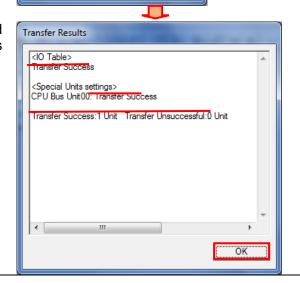
When the transfer is completed, Transfer Results Dialog Box is displayed.

Read the message in the dialog box and confirm that the transfer was normally executed.

When the I/O table is created normally, the dialog box shows the following:

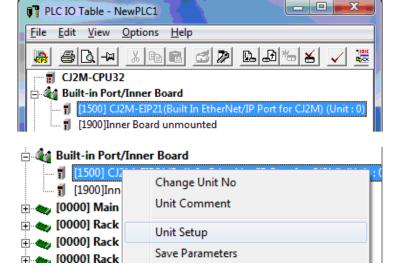
Transfer Success: 1 Unit Transfer Unsuccessful: 0 Unit

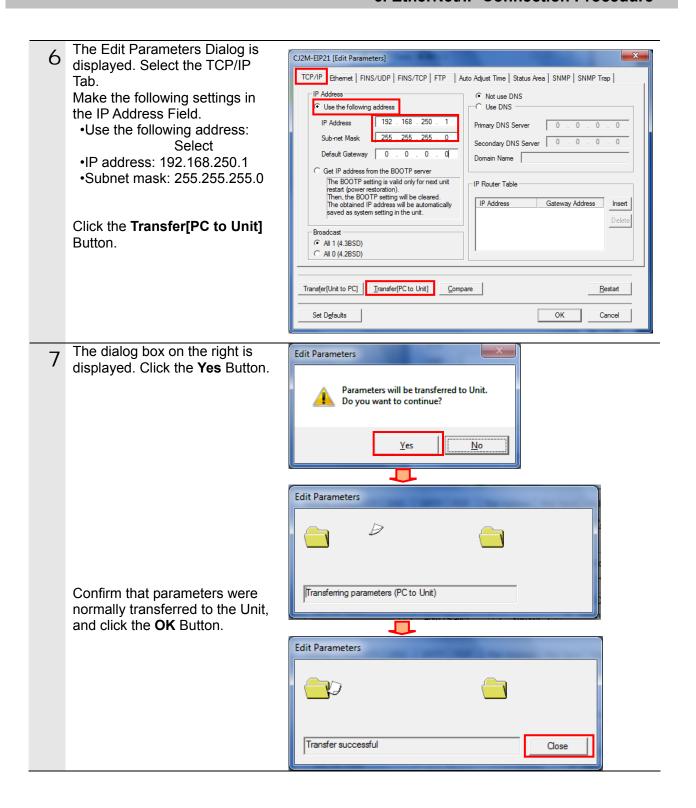
Click the **OK** Button.

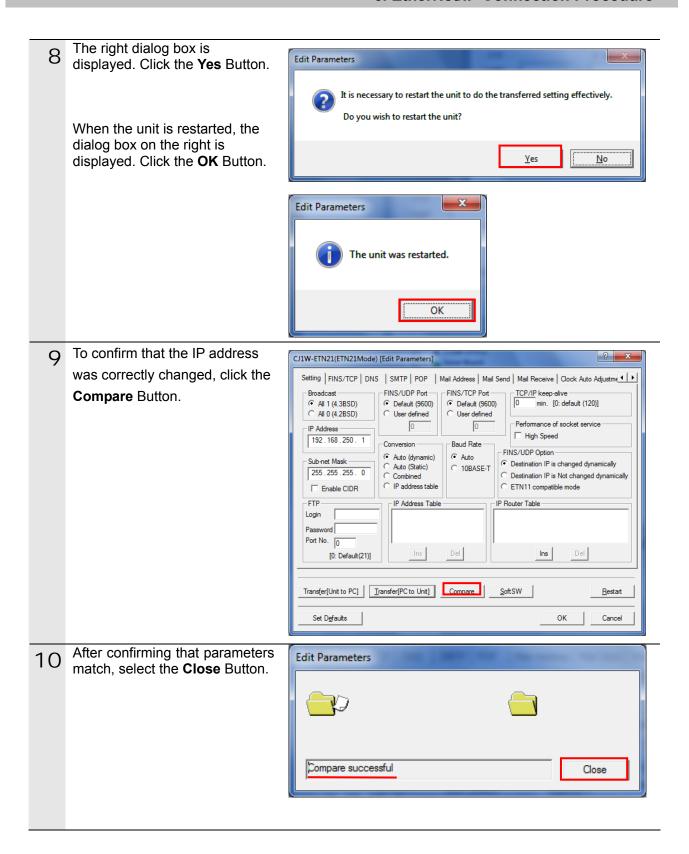


- On the PLC IO Table Window, click + to the left of Built-in Port/Inner Board to display CJ2M-EIP21.
 - *The right figure displays the CPU Unit (built-in EtherNet/IP port) specified in 5.2. Device Configuration. When you use an EtherNet/IP Unit not specified in 5.1. Applicable Devices, the display position and name are different from this figure.

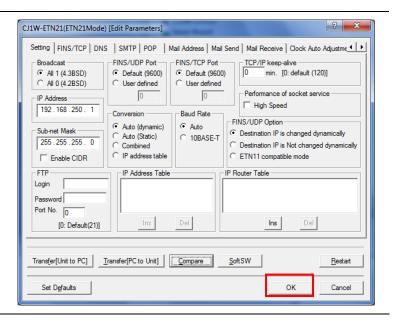
Right-click CJ2M-EIP21 and select *Unit Setup*.







On the Edit Parameters Dialog Box, click the **OK** Button.



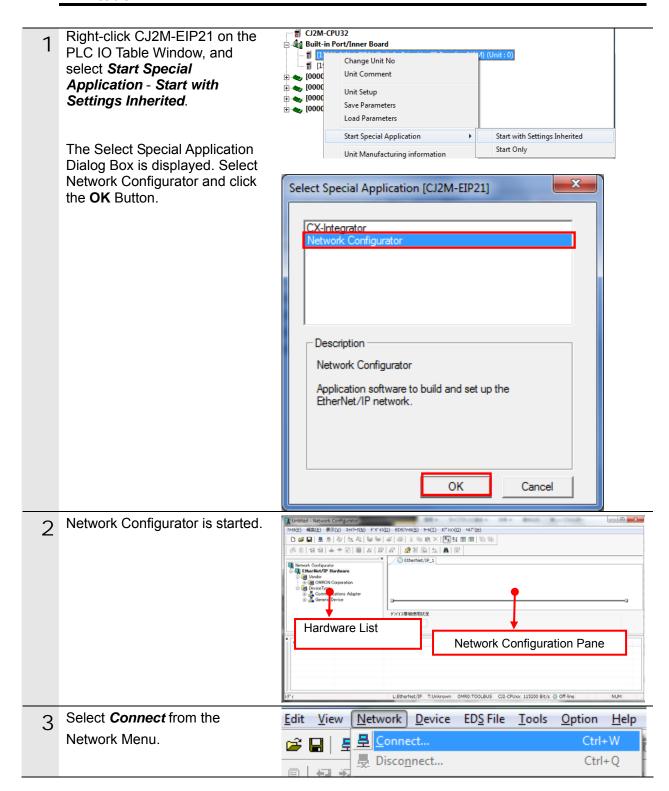
6.4.4. Starting the Network Configurator and Uploading the Configuration

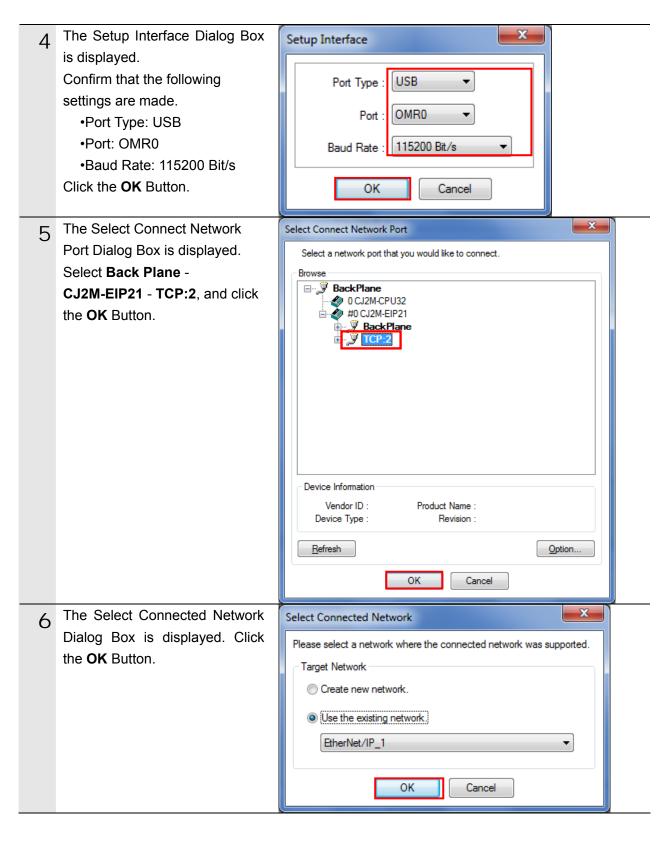
Start the Network Configurator and upload the network configuration.



Precautions for Correct Use

Please confirm that the LAN cable is connected before performing the following procedures. When it is not connected, turn OFF the power supply to each device and then connect the LAN cable.



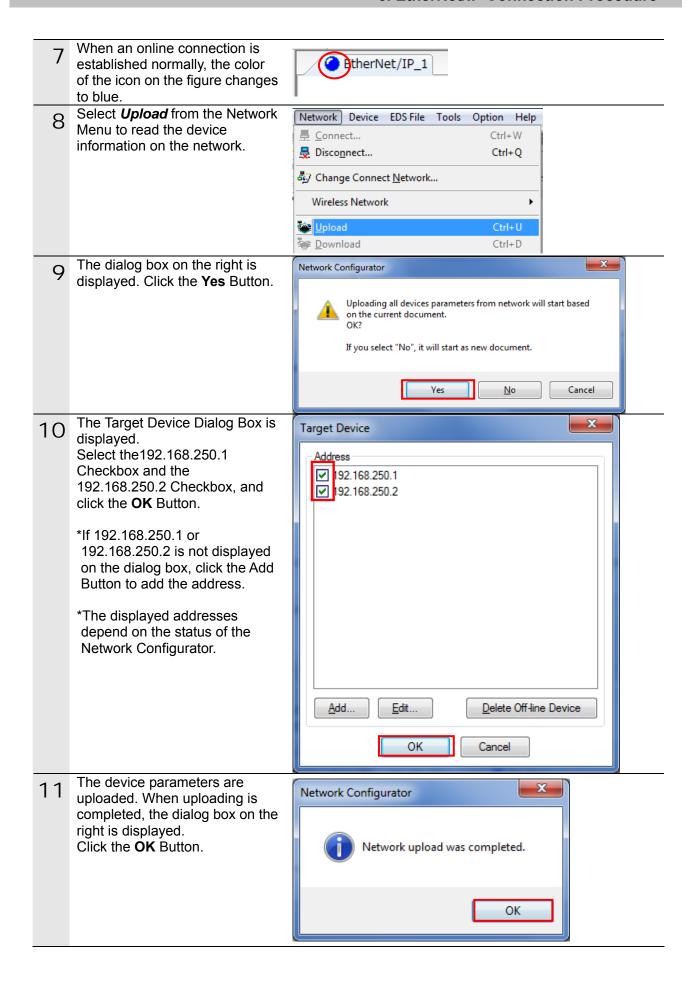




Additional Information

If the CX-Programmer and PLC are not connected online, please check the connection of the cable. Or, return to step 1, check the settings and try each step again.

For details, refer to 6-2-9 Connecting the Network Configurator to the Network in Section 6 Tag Data Link Functions of the EtherNet/IP Unit Operation Manual (Cat. No. W465).



6. EtherNet/IP Connection Procedure

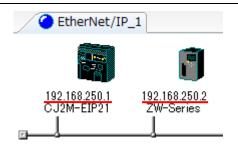
After uploading is completed, confirm that the Network Configuration Pane shows the updated IP addresses of the devices.

IP address of node 1:

192.168.250.1

IP address of node 2:

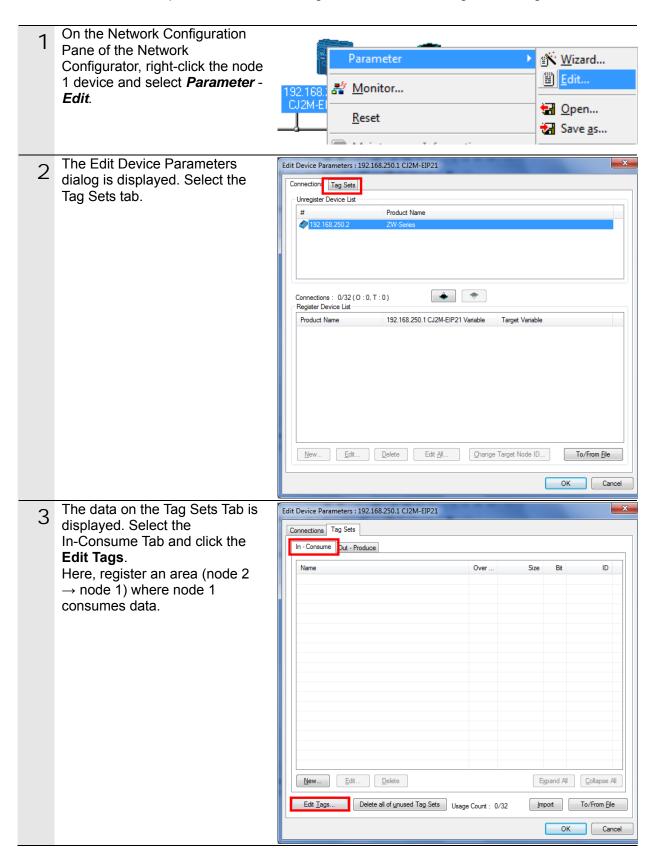
192.168.250.2



6.4.5. Setting Tags

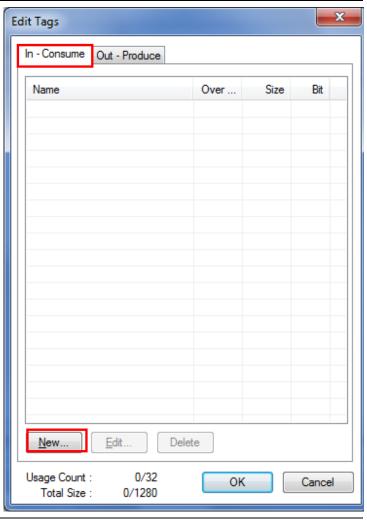
Register the tags of the receive area and send area.

This section explains the receive settings and then send settings of the target node.



The Edit Tags Dialog Box is displayed. Select the In - Consume Tab and click the **New** Button.

Here, register an area (node 2 \rightarrow node 1) where node 1 consumes data.



5 The Edit Tag Dialog Box is displayed.

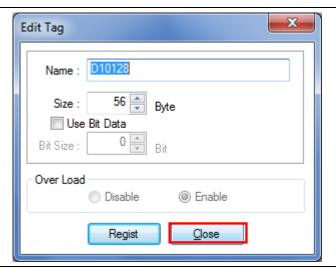
Enter the following values in the parameters.

- •Name: D10100 (Start address of the input data to node 1)
- •Size: 56 (bytes)

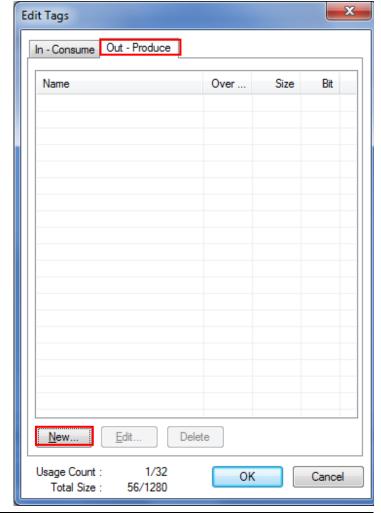
After entering, click the **Regist** Button.

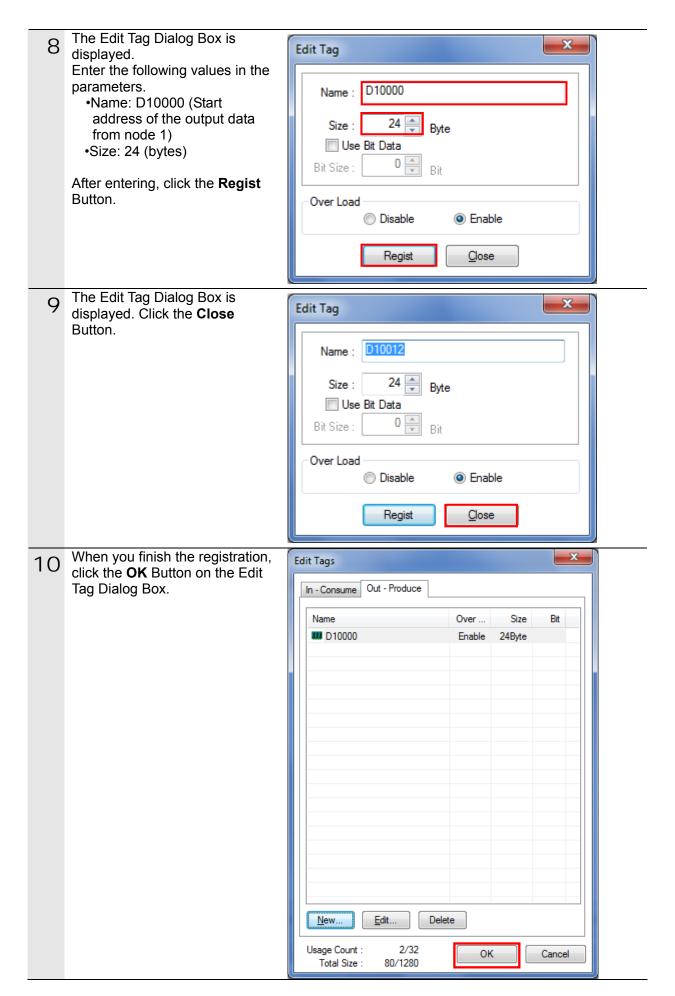


The Edit Tag Dialog Box is displayed. Click the **Close** Button.

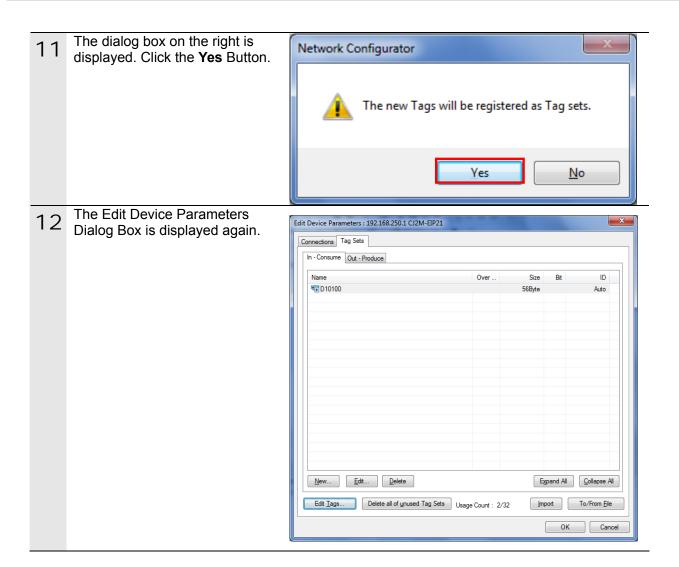


Select the Out - Produce Tab and click the New Button. Here, register the send data of node 1. (Data sent from node 1 to node 2).





6. EtherNet/IP Connection Procedure

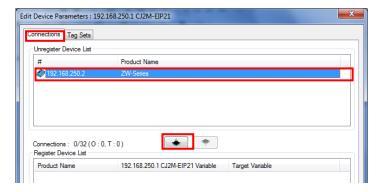


6.4.6. Setting Connections

Associate the tags of target device (node that receives the open request) with the tags of originator (node that requests opening).

1 Select the Connections Tab in the Edit Device Parameters Dialog Box.

Then, select 192.168.250.2 in the Unregister Device List Field. Click the Down Button that is shown in the dialog box.

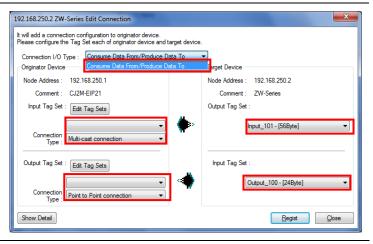


2 192.168.250.2 is registered in the Register Device List. Select 192.168.250.2 and click the **New** Button.



The Edit Connection Dialog Box is displayed. Select *Discrete Exclusive Owner* from the Connection I/O Type pull-down list.

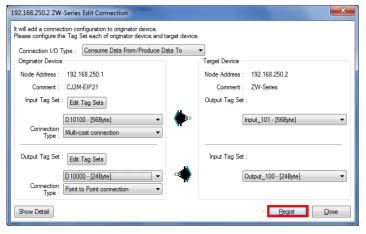
Set the values listed in the table below by using the pull-down lists in Originator Device Field and Target Device Field.



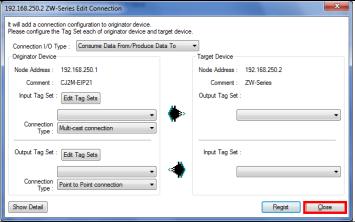
■Settings of Connection

Connection I/O type		Consume Data From/Produce Data To
Originator device	Input Tag Set	D10100 - [56Byte]
	Connection Type	Multi-cast connection
	Output Tag Set	D10000 - [24Byte]
	Connection Type	Point to Point connection
Target Device	Output Tag Set	Input_101- [56Byte]
	Input Tag Set	Output_100- [24Byte]

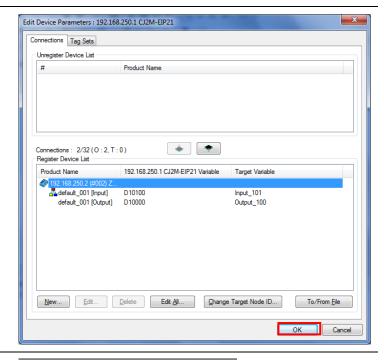
4 Confirm that the settings are correct and click the **Regist** Button.



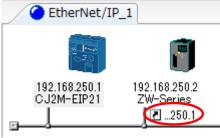
The Edit Connection Dialog Box is displayed. Do not make any setting and click the **Close** Button.



The Edit Device Parameters
Dialog Box is displayed again.
Click the **OK** Button.

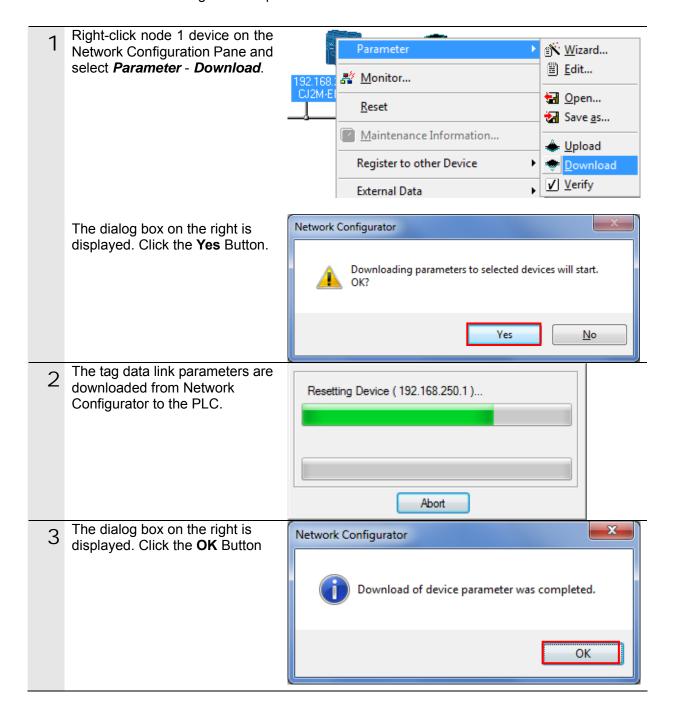


When the connection setting is completed, the registered node address is displayed under the device icon of node 2 on the Network Configuration Pane.



6.4.7. Transferring the Tag Data Link Parameters

Transfer the set tag data link parameters to the PLC.



6.5. Checking the EtherNet/IP Communications

Confirm that the EtherNet/IP communications are performed normally.

6.5.1. Checking the Connection Status

Check the connection status of EtherNet/IP.

1 Confirm that the tag data links are normally in operation by checking the status information on the Device Monitor Window of the Network Configurator.

•PLC (EtherNet/IP Unit)

LED indicators in normal status.

[MS]: Lit green [NS]: Lit green [COMM]: Lit yellow

[100M] or [10M]: Lit yellow

•Displacement Sensor

During normal connection, the red and green indicators on the ETHERNET connector are lit.

Confirm that the tag data links are normally in operation by checking the status information on the Device Monitor Window of the Network Configurator.

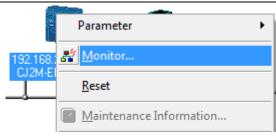
Right-click the device icon of node 1 on the Network Configuration Pane and select the *Monitor*.



(EtherNet/IP Unit)



(Displacement Sensor Controller)



6. EtherNet/IP Connection Procedure

The dialog box on the right displays Monitor Device the Status 1 Tab Page of the Device Controller Error History Ethernet Information Monitor Dialog Box. Status 1 Error History Unit Status Unit Error ✓ On-Line When the items in the right dialog ✓ Tag Data Link are selected, the data links are Unit Memory Error Change IP address in Run mode Enable User Specified Area Com. Controller Error normally in operation. IP Address Duplicated Multiple Switch ON LINK OFF Error Error History Status Area Layout Error Network Status ☐ IP Address Table Error Comparison Error Tag Data Link Error DNS Server Error Routing Table Error Invalid Parameter I/O Refresh Error Ethernet Ext Config Logical Error ✓ All Tag Data Link BOOTP Server Error SNTP Server Error ✓ Tag Data Link Address mismatch ✓ Ethernet Link Status Nonvolatile Memory Error Ethernet Config Logical Error Target Node Status-002 Number: Node number Blue: Connection normal Close Select Disconnect from the 4 EtherNet/IP_1

Select **Disconnect** from the Network Menu to go offline. The color of the icon on the figure changes from blue.

Select **Fxit** from the File Menu to

Select *Exit* from the File Menu to exit the Network Configurator.

6.5.2. Checking Data that are Sent and Received

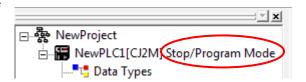
Confirm that correct data are sent and received.

Confirm safety sufficiently before monitoring power flow and present value status in the Ladder Section window or before monitoring present values in the Watch window. If force-set/reset or set/reset operations are incorrectly performed by pressing short-cut keys, the devices connected to Output Units may malfunction, regardless of the operating mode of the CPU Unit.

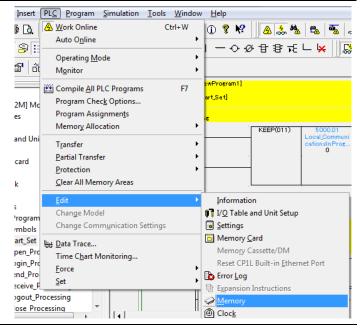


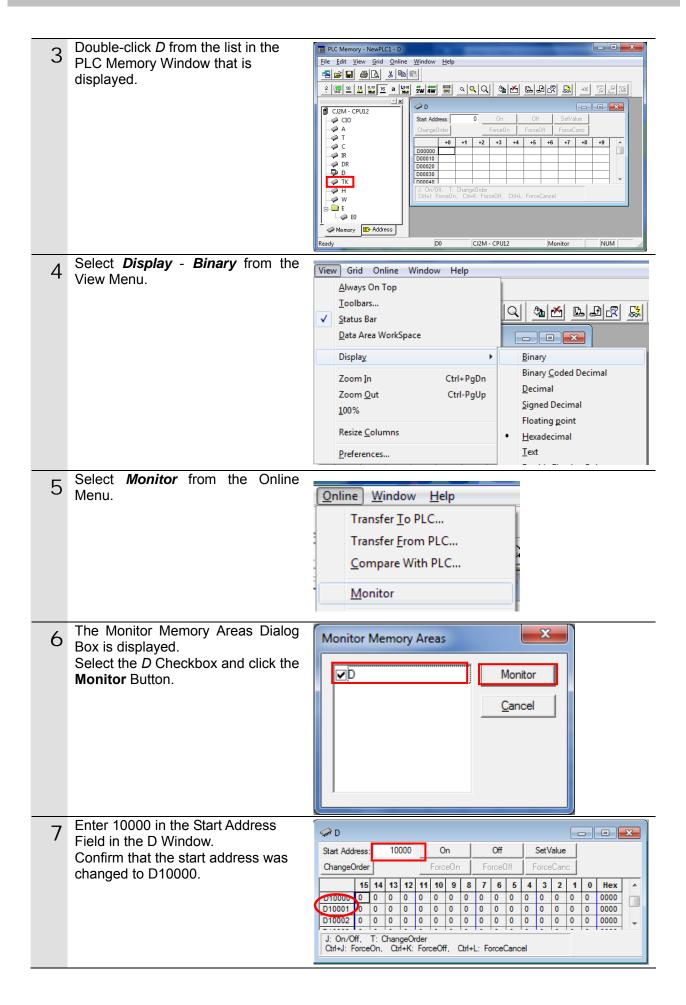
Confirm that the operating mode of the PLC is Stop/Program Mode.

*If the PLC is not in Program Mode, change to Program Mode by referring to step 1 of 6.4.3. Setting the IP Address.



2 Select *Edit* - *Memory* from the PLC Menu.





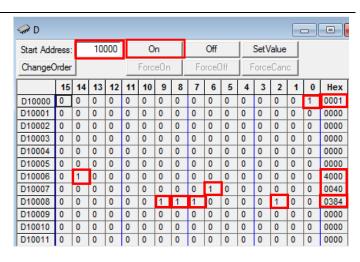
8 Select the bits below and click the On Button. (After turning them ON, the values change to 1.)
Bit 14 of DM10006
Bit 6 of DM10007
Bits 2, 7, 8, 9 of DM10008

Then, turn ON bit 0 of DM10000.

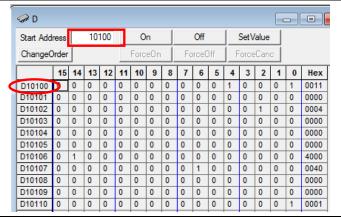
*DM10006 and DM10007 are an area for a command code and contain 4000 (Hex) and 0040 (Hex) (System data acquisition).

DM10008 is an area for Command Parameter 1 and contains 0384 (Hex) (900 in decimal) (the number of decimal places).

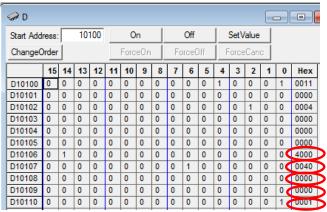
Bit 0 of D10000 is a command execution (EXE) flag.



Part Part 10100 in the Start Address Field on the D Window. Confirm that the start address was changed to D10100.



- 10 Confirm that values of DM10106 to DM10110 are set as shown on the right.
 - *DM10106 and DM10107 contain the command code, and DM10108 and DM10109 contain the command execution result (0: OK). DM10110 contains 0001 (Hex) (1 digit) that is response data (the number of decimal places).



Initialization Method

This document explains the setting procedure from the factory default setting.

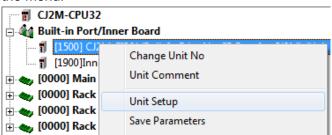
Some settings may not be applicable as described in this document unless you use the devices with the factory default setting.

7.1. Initializing the PLC

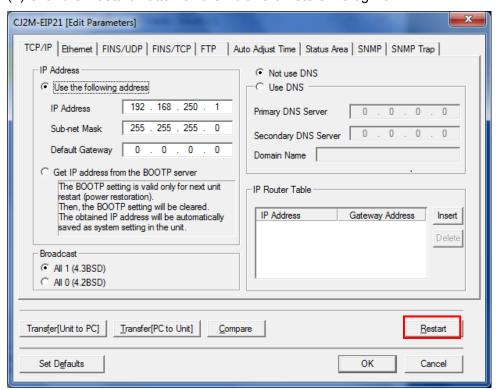
To initialize the settings of the PLC, you need to initialize the CPU Unit and EtherNet/IP Unit. Change to the PROGRAM mode before the initialization.

7.1.1. EtherNet/IP Unit

(1) Select Edit - I/O Table and Unit Setup from the PLC Menu of the CX-Programmer. Right-click the EtherNet/IP Unit on the PLC IO Table Window and select Unit Setup from the menu.



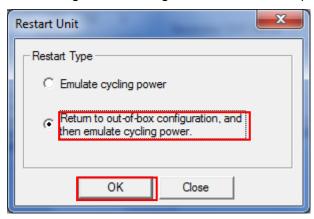
(2) Click the Restart Button on the Edit Parameters Dialog Box.



(3) An execution confirmation dialog is displayed. Click the Yes Button.

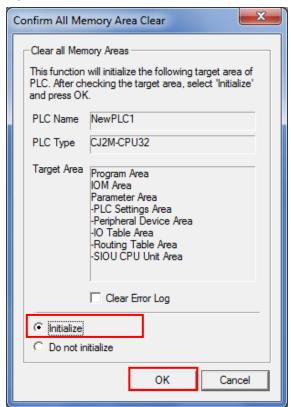
On the Restart Unit Dialog Box, select the *Return to out-of-box configuration, and then emulate cycling power* Option, and click the **OK** Button.

A dialog box indicating the execution is completed is displayed. Click the **OK** Button.



7.1.2. **CPU Unit**

To initialize the settings of the CPU Unit, select *Clear All Memory Areas* from the PLC Menu of the CX-Programmer. On the Confirm All Memory Area Clear Dialog Box, select the *Initialize* Option and click the **OK** Button.



7.2. Initializing the Displacement Sensor

For the initialization of the Displacement Sensor, refer to *Initializing Settings* under 9-11 Setting the System in the ZW Series Displacement Sensor (Confocal Fiber Type) User's Manual (Cat. No. Z332).

8. Revision History

Revision code	Date of revision	Revision reason and revision page
01	April 26, 2013	First edition

OMRON Corporation Industrial Automation Company

Tokyo, JAPAN

Contact: www.ia.omron.com

Regional Headquarters OMRON EUROPE B.V. Wegalaan 67-69-2132 JD Hoofddorp The Netherlands Tel: (31)2356-81-300/Fax: (31)2356-81-388

OMRON ASIA PACIFIC PTE. LTD. No. 438A Alexandra Road # 05-05/08 (Lobby 2), Alexandra Technopark, Singapore 119967 Tel: (65) 6835-3011/Fax: (65) 6835-2711

OMRON ELECTRONICS LLC One Commerce Drive Schaumburg, IL 60173-5302 U.S.A. Tel: (1) 847-843-7900/Fax: (1) 847-843-7787

OMRON (CHINA) CO., LTD.
Room 2211, Bank of China Tower,
200 Yin Cheng Zhong Road,
PuDong New Area, Shanghai, 200120, China
Tel: (86) 21-5037-2222/Fax: (86) 21-5037-2200

Authorized Distributor:

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